Proposal delivered (orally) to the supervisor:

- One robot speaks one language, while another speaks other language.

Problem:
- How can they learn each others languages by speaking their own languages only?

Hypothesis:
- If you give a robot an initial set of languages to communicate, it would be able to establish contact with a robot that speaks another language via own language (+ gestures)

- Give a robot a set of language speaking abilities
- Synthesize speaking
- Analyze sound
- Let it use its own learned (inate) language to interpret other language + construct more complex language constructs
- Give it a set of gestures to use
- Allow to interpret gestures

Possibilities:
- Be ablr to interpret any language (even imaginary)
- Robots may start using totally other language to communicate
- Robot may be placed with human being to set a communication without any prior specific programming (just like a baby). User will guide it (critic)

Origin:
- Star Trek TNG – race with most optimal (evolved) communication method